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FOR IMMEDIATE RELEASE

CAVATI DONATION ALLOWS UTAH UNIVERSITIES TO COMPETE IN DARPA URBAN CHALLENGE 2007

SALT LAKE CITY, JAN. 17 — Unmanned systems technology has taken another step forward in Utah.

Last week, the Center for Autonomous Vehicle Applied Technology and Information (CAVATI™) donated autonomous ground vehicles (AGVs) to two different Utah teams competing in the Defense Advanced Research Projects Agency (DARPA) Urban Challenge 2007.

A team from Brigham Young University in Provo, Utah, and another from the University of Utah in Salt Lake City each received a 2005 Dodge Caravan (blue and red, respectively) retrofitted with a Pronto4™ Universal Unmanned Vehicle Retrofit Kit from Kairos Autonomi™, a CAVATI™ Founding Member. CAVATI™ also donated funds to each university to support software development and the acquisition and integration of sensors for vehicle navigation systems.

Both university teams will compete in the Urban Challenge 2007, which will feature AGVs conducting simulated military supply missions in a mock urban area. Safe operation in traffic is essential to U.S. military plans to use AGVs to conduct important missions.

Using only their software and sensors, the retrofitted minivans will attempt to navigate the urban area in an unmanned, autonomous mode. The vehicles will be required to autonomously

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obey traffic laws while merging into moving traffic, negotiate busy intersections and avoid other vehicles, buildings and barriers.

“This donation fits perfectly with our mission to move forward unmanned vehicle technology by leveraging industry assets with university resources,” said George “Troy” Takach, Jr., Founding Member of CAVATI™. “By helping these two teams compete in the Urban Challenge 2007, CAVATI shows the nation that Utah is a key player in the unmanned systems industry.”

Donating the vehicles is one part of the State of Utah Unmanned, Autonomous Road Map (SWARM), a CAVATI™ initiative designed to foster unmanned systems collaboration among organizations in Utah.

Within SWARM, four primary objectives exist to increase unmanned systems business in Utah: bring autonomous vehicle contracts to Utah companies for execution; create a nationally recognized unmanned vehicle test facility; promote legislative initiatives to support AGV business and technology; and foster autonomous systems research through Utah universities.

CAVATI™ has been influential in doubling the number of Utah teams participating in the DARPA Urban Challenge 2007.

About CAVATI™

The Center for Autonomous Vehicle Applied Technology and Information (CAVATI™) is a non-profit, Utah-based business coalition with a mission to advance unmanned vehicle technology by leveraging industry assets with university resources in the state of Utah.

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